

Lecture 13 Independence, Rank, ~~basis~~, ~~dimension~~

Def. A set of vectors v_1, \dots, v_n is independent if none of the vectors can be written as LC of other vectors
(LC: linear combination) $\forall v_i, v_i \notin \text{Span}\{v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_n\}$
 $\Rightarrow v_1, \dots, v_n$ are dependent if one of the vectors can be written as LC of other vectors

Theorem v_1, \dots, v_n independent iff $[v_1, \dots, v_n] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = 0$
 $\Rightarrow x_1 = \dots = x_n = 0$ ($\Leftrightarrow \text{NullSpace}([v_1, \dots, v_n]) = \{0\}$.)

Proof. The theorem is equivalent to the following.

v_1, \dots, v_n dependent iff there's nonzero x

$$\text{s.t. } [v_1, \dots, v_n] x = 0. \quad x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$

Let's prove this equivalent form:

" \Rightarrow " w.o.l.g. v_1 is a linear combination of

$$v_2, v_3, \dots, v_n$$

$$v_1 = \alpha_2 v_2 + \dots + \alpha_n v_n$$

$$-v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = 0 \Rightarrow [v_1, v_2, \dots, v_n] \begin{bmatrix} -1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{bmatrix} = 0$$

$$\alpha = \begin{pmatrix} -1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{pmatrix} \neq 0.$$

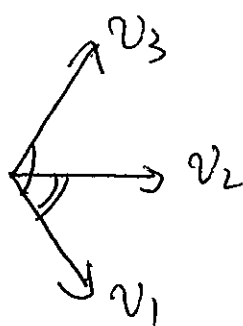
" \Leftarrow " let $\alpha \neq 0$ and $[v_1, \dots, v_n] \alpha = 0$.

w.o.l.g. $\alpha_1 \neq 0$. $\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = 0$

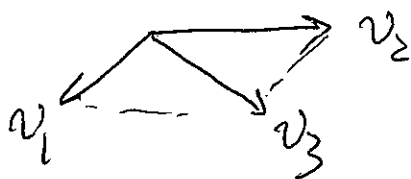
$$v_1 = -\left(\frac{\alpha_2}{\alpha_1}\right)v_2 + \dots + \left(\frac{\alpha_n}{\alpha_1}\right)v_n.$$

We can say there's no extra vectors in an independent set because none can be written as LC of other vectors; each vector in the set needs to contribute something new.

Geometrically,



independent.



dependent.

Some examples: 1) $0, v_2, \dots, v_n$ dependent.

2) $v_1, 2v_1, v_3, \dots, v_n$ dependent.

3) Columns of $I_n = (e_1, \dots, e_n)$ independent.
cols of

4) \wedge Triangular matrices independent iff. diagonal elements are nonzero

5) $A \in \mathbb{R}^{n \times n}$, cols of A independent iff A

invertible, i.e. there's X s.t. $XA=I$,

6) cols of A dependent \Rightarrow cols of $[A, B]$ dependent. $AX=I$.

7) cols of A independent \Rightarrow cols of $\begin{pmatrix} A \\ B \end{pmatrix}$ independent.
 \Rightarrow a subset of cols of A is also independent

8) $A \in \mathbb{R}^{n \times n}$, A has independent cols iff $Ax=b$ has unique solution $\forall b \in \mathbb{R}^n$.

9) $A \in \mathbb{R}^{n \times n}$, A has independent cols iff A^T has independent cols. (proof. \Rightarrow If $\$$ is s.t. $A^T u = 0$,

we need to show $u=0$. A cols independent, $\exists x$, $Ax = \$ u$

$A^T A x = 0 \Rightarrow u^T A^T A x = 0$. $(A^T A x)^T = 0 \Rightarrow Ax = 0$.

$A \in \mathbb{R}^{m \times n}$, if A has independent col's, we say
 $(A \in \mathbb{R}^{m \times n}, B \in \mathbb{R}^{n \times p})$
 A, B full col rank $\Rightarrow AB$ full col rank

A has full column rank. In this case: $m \geq n$.

and $Ax=0 \Rightarrow x=0$.

10) In fact, if $m < n$, ~~A has independent col's.~~

col's of A are dependent. (Such matrix is called a fat matrix)

Proof. take the first m col's of A , call it $A_1 \in \mathbb{R}^{m \times m}$

1) if A_1 has independent col's. Consider

$$[A_1, A_2] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0. \quad x_1 = -A_1^{-1} A_2 x_2$$

Select an arbitrary $x_2 \neq 0$, compute x_1 as above

then $x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \neq 0$, and $Ax=0 \Rightarrow$ col's A dependent.

2) if A_1 has dependent col's, then of course $[A_1, A_2]$ has dependent col's. #

one-step of

There's another approach using induction on m , and GTE

11) If $A \in \mathbb{R}^{m \times m}$ is invertible, and v_1, \dots, v_m are independent, then Av_1, \dots, Av_m are also independent

proof. Consider, $[Av_1, \dots, Av_m]x = 0$.

$$A[v_1, \dots, v_m]x = 0 \Rightarrow [v_1, \dots, v_m]x = 0 \Rightarrow x = 0.$$

12) Independence and RREF: Pivot cols of RREF (or REF)

of $A \in \mathbb{R}^{m \times n}$ gives the first r independent cols of A : r is the rank of A , $r = \text{rank}(A)$ (col rank = row rank)

rank which is defined to be the maximal number of ~~inde~~ independent cols of A .

$$\left[\begin{array}{cccc} 0 & \dots & 1 & * \dots * 0 * \dots * 0 * \dots * \\ & & & 1 * \dots * 0 * \dots * \\ & & & \vdots \\ & & & 1 * \dots * \\ \hline & & 0 & \dots & 0 \end{array} \right] \in \mathbb{R}^{m \times n}$$

$A = [a_1, \dots, a_n]$

$\downarrow \quad \downarrow \quad \downarrow$
 $n_1 \quad n_2 \quad \dots \quad n_r$

$\left\{ a_{n_1}, a_{n_2}, \dots, a_{n_r} \right\}$
 are independent!

rank of a set of vectors

$$S = \{v_1, \dots, v_n\}$$

Form the matrix $V = (v_1, \dots, v_n)$,

the rank of $S = \text{rank}(V)$. This is the same as ^{the # of vectors in} the maximal linearly independent system of S .

$\{v_{n_1}, \dots, v_{n_k}\}$ linearly independent,

but adding another vector v_j into the above,

they become dependent.

The computation of REF/RREF of $V = (v_1, \dots, v_n)$ can find the maximal linearly independent system.

Properties of matrix rank:

12) $A \in \mathbb{R}^{m \times n}$, $B \in \mathbb{R}^{n \times p}$, then

$$\text{rank}(AB) \leq \text{rank}(A), \text{rank}(AB) \leq \text{rank}(B)$$

Proof. we first prove the 2nd one. use the following fact: if v_1, \dots, v_n are dependent, then

Av_1, \dots, Av_n are also dependent
for any matrix A s.t. Av_i is defined.

Now let $B = (b_1, \dots, b_n)$, then for any subset of

cols of B , say b_{i_1}, \dots, b_{i_k} , if $k > \text{rank}(B)$

this set of cols is dependent. \Rightarrow

$Ab_{i_1}, \dots, Ab_{i_k}$ are dependent.

\Rightarrow Any k cols of AB , if $k > \text{rank}(B)$, are dependent.

hence $\text{rank}(AB) \leq \text{rank}(B)$

Now $\text{rank}(AB) = \text{rank}((AB)^T) = \text{rank}(B^T A^T)$

$\leq \text{rank}(A^T) = \text{rank}(A)$

$$(14) \text{rank}(A) \leq \text{rank}([A, B])$$

Proof. The maximal # of independent cols can only increase by adding more vectors to the set.

$$(15) \text{ } Ax=b \text{ has a solution iff } \text{rank}(A) = \text{rank}([A, b])$$

The coefficient matrix A and the augmented matrix

$[A, b]$ have the same rank

Proof. " \Rightarrow " $r(A) \leq r([A, b])$, now let $Ax_0 = b$.

then $[A, b] = [A, Ax_0] = A[I, x_0] \Rightarrow r([A, b]) \leq r(A)$

" \Leftarrow " let the $r = \text{rank}(A) = r([A, b])$, and

w.o.l.g. a_1, \dots, a_r independent, then

a_1, \dots, a_r, b are dependent. We have non-zero

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_r \\ x_{r+1} \end{pmatrix} \neq 0, \text{ s.t. } [a_1, \dots, a_r, b] \begin{pmatrix} x_1 \\ \vdots \\ x_r \\ x_{r+1} \end{pmatrix} = 0.$$

$x_{r+1} \neq 0$, otherwise $\begin{pmatrix} x_1 \\ \vdots \\ x_r \end{pmatrix} \neq 0$, but $[a_1, \dots, a_r] \begin{pmatrix} x_1 \\ \vdots \\ x_r \end{pmatrix} = 0$.

$$\text{Then } b = A \begin{bmatrix} -x_1/x_{r+1} \\ \vdots \\ -x_r/x_{r+1} \end{bmatrix}$$

$$16) \quad r(ATA) = r(A). \quad r(ATA) \leq r(A).$$

let $r = r(A)$, we show ATA has r independent cols, w.o.l.g. a_1, \dots, a_r independent.

We show ATA_1, \dots, ATA_r are also independent.

$$\text{In fact, } [ATA_1, \dots, ATA_r]x = 0 \Rightarrow$$

$$\begin{pmatrix} a_1^T \\ \vdots \\ a_r^T \end{pmatrix} [a_1, \dots, a_r]x = 0 \Rightarrow$$

$$x^T \begin{pmatrix} a_1^T \\ \vdots \\ a_r^T \end{pmatrix} [a_1, \dots, a_r]x = 0 \Rightarrow [a_1, \dots, a_r]x = 0$$

$$\Rightarrow x = 0 \text{ since } a_1, \dots, a_r \text{ independent.}$$

17) $ATAx = A^Tb$ always has a solution.

$$\forall b \quad r([ATA, A^Tb]) = r(ATA) = r(A)$$

$$18) \quad r([A, B]) \leq r(A) + r(B)$$

Proof. Given any subset of columns of

$[A, B]$ with size more than $(> r(A) + r(B))$

then either more than $r(A)$ col's come from A or

more than $r(B)$ col's come from B. But ~~either~~ ^{both} of these

two sets are dependent, hence this given subset of

$[A, B]$ is dependent.

$$19) \quad r \left(\begin{pmatrix} A & 0 \\ 0 & B \end{pmatrix} \right) = r(A) + r(B)$$

$$r \left(\begin{pmatrix} A & C \\ 0 & B \end{pmatrix} \right) \leq r(A) + r(B) + r(C), \text{ equality can be achieved.}$$

20.) If B, C are nonsingular matrices, then

$$r(BAC) = r(A)$$

This is a useful result, it implies that we can use elimination matrices B and C to simplify A in order to find the rank of A .

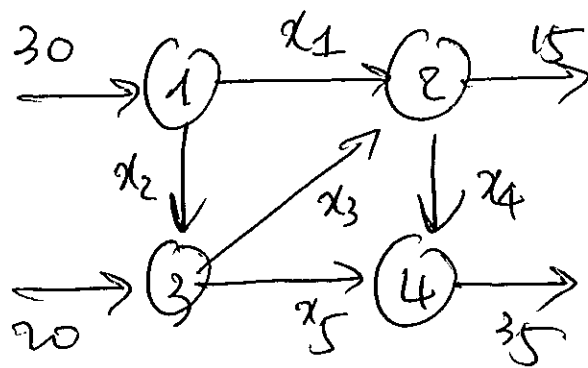
$$\mathbb{R}^{n \times n} \rightarrow A = \left(\begin{array}{c|c} a_{11} & u^T \\ \hline c_1 & A_1 \end{array} \right) \rightarrow \left(\begin{array}{c|c} a_{11} & 0 \\ \hline 0 & A_1 - a_1 u^T / a_{11} \end{array} \right)$$

assume $a_{11} \neq 0$.

$$\text{Then } r(A) = 1 + r(A_1 - a_1 u^T / a_{11})$$

In particular, if $r(A) = n$, then $A_1 - a_1 u^T / a_{11}$ is also nonsingular.

Flow of traffic through a road network



We have measurements on certain road segments and we want to figure out those on other segs.

$$\text{Node 1: } x_1 + x_2 = 30$$

$$\text{Node 2: } x_1 + x_3 - x_4 = 15$$

$$\text{Node 3: } x_3 + x_5 - x_2 = 20$$

$$\text{Node 4: } x_4 + x_5 = 35$$

In matrix format.

$$\begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & -1 & 0 \\ 0 & -1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 30 \\ 15 \\ 20 \\ 35 \end{bmatrix}$$

~~RREF.~~

$$\left[\begin{array}{ccccc|c} \textcircled{1} & 1 & 0 & 0 & 0 & 30 \\ 0 & \textcircled{1} & -1 & 1 & 0 & 15 \\ 0 & 0 & 0 & \textcircled{1} & 1 & 35 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

RREF

$$\left[\begin{array}{ccccc|c} \textcircled{1} & 0 & 1 & \textcircled{1} & \textcircled{1} & 35 \\ 0 & \textcircled{1} & -1 & 0 & -1 & -20 \\ 0 & 0 & 0 & \textcircled{1} & 1 & 35 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

$$\begin{cases} x_1 = 35 - x_3 - x_5 \\ x_2 = -20 + x_3 + x_5 \\ x_4 = 35 - x_5 \end{cases} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} 35 \\ -20 \\ 0 \\ 35 \\ 0 \end{pmatrix} + \begin{pmatrix} -1 & -1 \\ 1 & 1 \\ 1 & 0 \\ 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x_3 \\ x_5 \end{pmatrix}$$