

## lecture 18

# Gram-Schmidt Orthogonalization

For simplicity, assume col's of  $A = (a_1, \dots, a_n)$  are independent. We want find orthogonal matrix  $Q \in \mathbb{R}^{m \times n}$ , upper tri.  $R \in \mathbb{R}^{n \times n}$ , s.t.

$$A = QR$$

This is the QR decomposition of  $A$ .

$$[a_1, \dots, a_n] = [z_1, \dots, z_n] \begin{bmatrix} r_{11} & r_{12} & \dots & r_{1n} \\ & r_{22} & & \vdots \\ & & \ddots & \\ & & & r_{nn} \end{bmatrix}$$

For the 1st-col from both sides

$$a_1 = r_{11} z_1.$$

$a_1 \neq 0$ , we choose  $r_{11} = \|a_1\|$ , and  $z_1 = a_1 / r_{11}$

Recall  $Q$  is orthonormal,  $q_i^T q_j = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$

From the 2nd col of both sides

$$a_2 = r_{12} q_1 + r_{22} q_2.$$

Pre-multiply with  $q_1^T$  on both sides

$$q_1^T a_2 = r_{12} \underbrace{q_1^T q_1}_{=1} + r_{22} \underbrace{q_1^T q_2}_{=0}.$$

$$r_{12} = q_1^T a_2.$$

$$\text{Now } r_{22} q_2 = a_2 - r_{12} q_1 \equiv \hat{q}_2$$

We can choose  $r_{22} = \|\hat{q}_2\|$ , and  $q_2 = \hat{q}_2 / r_{22}$

because  $\hat{q}_2 \neq 0$

Assume we have computed  $\beta_1, \dots, \beta_{k-1}$  and the first  $(k-1)$ -cols of  $R$ .

From the  $k$ -th of both sides of  $A = QR$

$$a_k = r_{1k} \beta_1 + r_{2k} \beta_2 + \dots + r_{k-1,k} \beta_{k-1} + r_{kk} \beta_k$$

Use the fact,  $\beta_i^T \beta_j = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$ .

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We find  $r_{1k} = \beta_1^T a_k, r_{2k} = \beta_2^T a_k, \dots, r_{k-1,k} = \beta_{k-1}^T a_k$

Now  $r_{kk} \beta_k = a_k - (r_{1k} \beta_1 + \dots + r_{k-1,k} \beta_{k-1}) \equiv \hat{\beta}_k$ ,  
again  $\hat{\beta}_k \neq 0$ , we choose  $r_{kk} = \|\hat{\beta}_k\|, \beta_k = \hat{\beta}_k / r_{kk}$

$$\text{In } \mathbb{R}^3, \quad a_1 = \begin{pmatrix} 3 \\ 0 \\ 4 \end{pmatrix}, \quad a_2 = \begin{pmatrix} -1 \\ 0 \\ 7 \end{pmatrix}, \quad a_3 = \begin{pmatrix} 2 \\ 9 \\ 11 \end{pmatrix}$$

When computing by hand, it's also possible not to normalize during GS, but rather carry out normalization at the end.

$$\tilde{b}_1 = \begin{pmatrix} 3 \\ 0 \\ 4 \end{pmatrix}, \quad \tilde{b}_2 = \begin{pmatrix} -1 \\ 0 \\ 7 \end{pmatrix} - \frac{-1 \cdot 3 + 0 + 7 \cdot 4}{25} \begin{pmatrix} 3 \\ 0 \\ 4 \end{pmatrix} = \begin{pmatrix} -4 \\ 0 \\ 3 \end{pmatrix}$$

$$\begin{aligned} \tilde{b}_3 &= \begin{pmatrix} 2 \\ 9 \\ 11 \end{pmatrix} - \frac{2 \cdot 3 + 0 + 11 \cdot 4}{25} \begin{pmatrix} 3 \\ 0 \\ 4 \end{pmatrix} - \frac{2 \cdot (-4) + 0 + 11 \cdot 3}{25} \begin{pmatrix} -4 \\ 0 \\ 3 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 9 \\ 0 \end{pmatrix} \end{aligned}$$

$$b_1 = \frac{1}{5} \begin{pmatrix} 3 \\ 0 \\ 4 \end{pmatrix}, \quad b_2 = \frac{1}{5} \begin{pmatrix} -4 \\ 0 \\ 3 \end{pmatrix}, \quad b_3 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

For the case  $A$  has independent cols, the least squares  $\min_x \|b - Ax\|^2$  is unique

1) Compute  $b_1 = Q^T b$

2) Solve  $Rx = b_1$ .

Properties of LS:

1).  $\text{Span}\{a_1, \dots, a_k\} = \text{Span}\{z_1, \dots, z_k\}$   
for any  $k=1, \dots, n$ . This is to say  
 $\{z_1, \dots, z_k\}$  forms an orthonormal basis for  $\text{Span}\{a_1, \dots, a_k\}$   
and  $\{z_1, \dots, z_n\}$  forms an orthonormal basis for  $C(A)$ .

2). The least squares problem

$$\min_x \|[z_1 \dots z_k]x - a_k\|^2$$

has sol  $x = \begin{pmatrix} \beta_1^T a_k \\ \vdots \\ \beta_{k-1}^T a_k \end{pmatrix} = \begin{pmatrix} r_{1k} \\ \vdots \\ r_{k-1,k} \end{pmatrix}$

Hence  $[\beta_1, \dots, \beta_{k-1}] \begin{pmatrix} r_{1k} \\ \vdots \\ r_{k-1,k} \end{pmatrix}$  is the orthogonal projection of  $a_k$

$$\hat{a}_k = a_k - [\beta_1, \dots, \beta_{k-1}] \begin{bmatrix} r_{1k} \\ \vdots \\ r_{k-1,k} \end{bmatrix} \quad \begin{array}{l} \text{onto } \text{Span}\{\beta_1, \dots, \beta_{k-1}\} \\ = \text{Span}\{a_1, \dots, a_{k-1}\} \end{array}$$

is the residual.

Old problem with a new proof.

$$Q^T Q = I_n \Rightarrow Q Q^T = I_n$$

Notice  $Q = [\beta_1, \dots, \beta_n]$   $Q^T Q = I \Rightarrow \|\beta_1\| = 1$ .

Use Householder  $H_1$ :  $H_1 \beta_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \end{pmatrix} = e_1$ .

$$H_1 = H_1^T, H_1^2 = I$$

$$I = (H_1 Q)^T (H_1 Q) = \left( \begin{array}{c|ccc} 1 & 0 & \dots & 0 \\ \hline \alpha_1 & & & * \end{array} \right) \left( \begin{array}{c|ccc} \alpha_1 & & & \alpha_1^T \\ \hline 0 & & & * \\ \vdots & & & \end{array} \right) \Rightarrow u_1^T = 0.$$

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$$H_1 Q = \left( \begin{array}{c|c} 1 & 0 \\ \hline 0 & Q_1 \end{array} \right) \quad \text{and} \quad Q_1^T Q_1 = I_{n-1}$$

A sequence of Householder  $H_{n-1} \dots H_1 Q = I$ .

$$Q = H_1 \dots H_{n-1}, \quad Q Q^T = H_1 \dots H_{n-1} H_{n-1} \dots H_1 = I$$