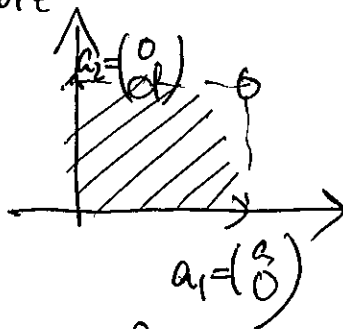


Lecture 19 Determinants

$$A \in \mathbb{R}^{2 \times 2}, \quad A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}, \quad \det A = ad - bc$$

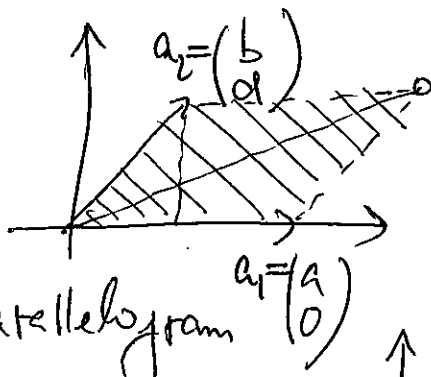
What is the geometric picture?

$$A = \begin{pmatrix} a & | & 0 \\ 0 & | & d \\ \hline a_1 & & a_2 \end{pmatrix}$$



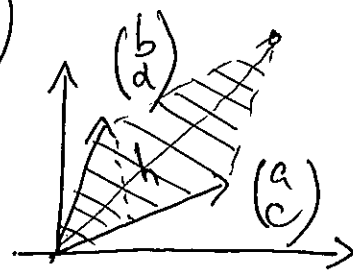
Area of rectangle = ad .

$$A = \begin{pmatrix} a & | & b \\ 0 & | & d \\ \hline a_1 & & a_2 \end{pmatrix}$$



$ad = \text{Area of } \text{parallelogram}$

Now for general $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$



We can rotate $a_1 = \begin{pmatrix} a \\ c \end{pmatrix}$ to $\begin{pmatrix} \|a\| \\ 0 \end{pmatrix}$ $\begin{pmatrix} b \\ d \end{pmatrix}$ will be rotated to $\begin{pmatrix} * \\ h \end{pmatrix}$

$\|a\| \cdot h = \text{Area of parallelogram, because rotation}$

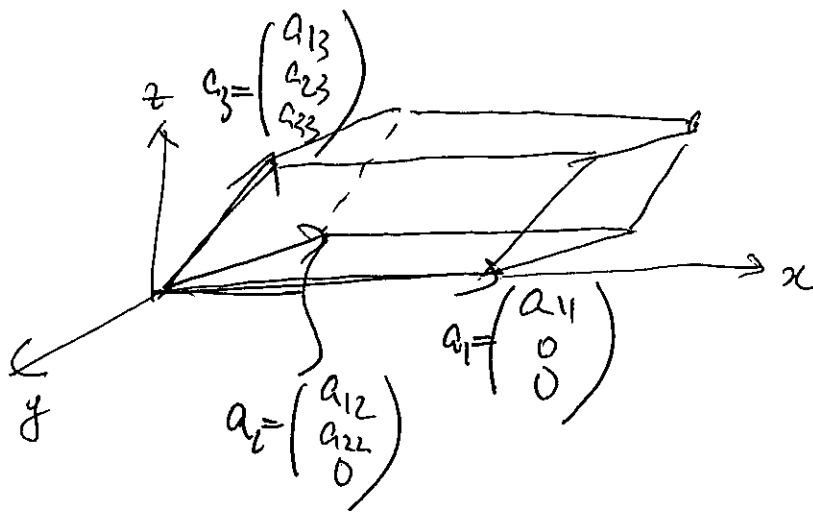
preserves area

It's not hard to extend the above argument to \mathbb{R}^3 . For example

$$\det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & 0 & a_{33} \end{pmatrix} = a_{11} a_{22} a_{33}$$

The box with corners $a_1 = \begin{pmatrix} a_{11} \\ 0 \\ 0 \end{pmatrix}$, $a_2 = \begin{pmatrix} a_{12} \\ a_{22} \\ 0 \end{pmatrix}$, $a_3 = \begin{pmatrix} a_{13} \\ a_{23} \\ a_{33} \end{pmatrix}$
(or edges)

has volume $a_{11} a_{22} a_{33}$



Now for any $A = (a_1, a_2, a_3) \in \mathbb{R}^{3 \times 3}$, there's ortho.

$$Q : QA = (Qa_1, Qa_2, Qa_3) = \begin{pmatrix} r_{11} & r_{12} & r_{13} \\ & r_{22} & r_{23} \\ & & r_{33} \end{pmatrix}$$

$$\begin{aligned} \text{Volume of box with corners } a_1, a_2, a_3 &= |r_{11} r_{22} r_{33}| \\ &= |\det A| \text{ Absolute value of } \det A \end{aligned}$$

In general,

For $A = [a_1, \dots, a_n] \in \mathbb{R}^{n \times n}$, $|\det A|$ is the

Volume of the box with corners a_1, a_2, \dots, a_n .

We can also appeal to QR decomposition of A .

$$A = QR, \quad Q \text{ ortho.} \quad R = \begin{pmatrix} r_{11} & * \\ & \ddots \\ 0 & & r_{nn} \end{pmatrix}$$

$$|\det A| = \underbrace{|\sigma_{11} \dots \sigma_{nn}|}_{\text{product of diagonals of } R}$$

Properties of determinants

1. $\det : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$. $\det A \in \mathbb{R}$.

a mapping from $\mathbb{R}^{n \times n}$ to \mathbb{R} , i.e. for any square matrix A , assign a real number $\det A$

\Rightarrow 2. $\det(AB) = \det A \det B$

3. let $A = (a_1, \dots, a_n)$, for scalar α .

$$\det(\alpha a_1, a_2, \dots, a_n) = \alpha \det A.$$

Since $\det \begin{pmatrix} \alpha & & \\ & 1 & \\ & & \ddots \\ & & & 1 \end{pmatrix} = \alpha$, and $[\alpha a_1, \dots, a_n] = A \begin{pmatrix} \alpha & & \\ & 1 & \\ & & \ddots \\ & & & 1 \end{pmatrix}$

4. pre- and post-multiply with elimination

matrices do not change the determinant.

5. If A is nonsingular $\Rightarrow \det A^{-1} = (\det A)^{-1}$

6. $\det A^T = \det A$.

Proof. $A = PLU$. $\det A = \det P \det L \det U$
 $= \det P (u_{11} \dots u_{nn})$
 $A^T = U^T L^T P^T$, $\det A^T = \det P^T (u_{11} \dots u_{nn})$

but. $P^T = P^{-1}$ $\det P^T = (\det P)^{-1} = \det P$

since $\det P = \pm 1$.

$\det \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = -1$. Any permutation = product of transpositions (not necessarily unique, but ~~have~~ ^{have} the same parity)

7. A is nonsingular iff $\det A \neq 0$

8. $\det \begin{pmatrix} A & B \\ 0 & C \end{pmatrix} = \det A \det C$ where A, B square

9. $\det [u+v, a_2, \dots, a_n] = \det [u, a_2, \dots, a_n] + \det [v, a_2, \dots, a_n]$

Proof. If $\underbrace{a_2, \dots, a_n}$ are dependent, then all 3 matrices are singular. $\det = 0$

So assume a_2, \dots, a_n independent, then if u, a_2, \dots, a_n dependent, and v, a_2, \dots, a_n dependent.

$\Rightarrow u+v, a_2, \dots, a_n$ dependent. all 3 matrices have $\det = 0$

Now assume u, a_2, \dots, a_n independent, then

$v = \alpha_1 u + \alpha_2 a_2 + \dots + \alpha_n a_n$, a linear combination of the basis vectors

$$\det [u+V, a_2, \dots, a_n]$$

use elimination!

$$= \det [(1+\alpha_1)u + \alpha_2 a_2 + \dots + \alpha_n a_n, a_2, \dots, a_n]$$

$$= \det [(1+\alpha_1)u, a_2, \dots, a_n] = (1+\alpha_1) \det [u, a_2, \dots, a_n]$$

$$\det [V, a_2, \dots, a_n] = \det [\alpha_1 u + \alpha_2 a_2 + \dots + \alpha_n a_n, a_2, \dots, a_n]$$

$$= \det [\alpha_1 u, a_2, \dots, a_n] = \alpha_1 \det [u, a_2, \dots, a_n]$$

$$\det [u, a_2, \dots, a_n] + \det [V, a_2, \dots, a_n] = (1+\alpha_1) \det [u, a_2, \dots, a_n]$$

$$10. \det [\alpha u + \beta v, a_2, \dots, a_n] = \alpha \det [u, a_2, \dots, a_n] + \beta \det [v, a_2, \dots, a_n]$$

Therefore $\det A$ is a multi-linear function considered as functions of a_1, \dots, a_n (linear in each argument a_1, \dots, a_n)

11. Exchanging two rows (or two cols) of a matrix changes the sign of its determinant.

12. Cofactors

Consider $A = (a_1, a_2, \dots, a_n)$

$$\text{assume: } a_1 = \begin{pmatrix} a_{11} \\ 0 \\ \vdots \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ a_{21} \\ 0 \\ \vdots \\ 0 \end{pmatrix} + \dots + \begin{pmatrix} 0 \\ \vdots \\ 0 \\ a_{n1} \end{pmatrix}$$

$$\det A = \det \left[\begin{pmatrix} a_{11} \\ 0 \\ \vdots \\ 0 \end{pmatrix}, a_2, \dots, a_n \right] + \det \left[\begin{pmatrix} 0 \\ a_{21} \\ 0 \\ \vdots \\ 0 \end{pmatrix}, a_2, \dots, a_n \right]$$

$$+ \dots + \det \left[\begin{pmatrix} 0 \\ \vdots \\ 0 \\ a_{n1} \end{pmatrix}, a_2, \dots, a_n \right], \text{ expansion}$$

$$\text{Now } \det \left[\begin{pmatrix} a_{11} \\ 0 \\ \vdots \\ 0 \end{pmatrix}, a_2, \dots, a_n \right] = a_{11} \det A(1,1)$$

where $A(1,1)$ is A with its 1st row and 1 col removed

$$\det \left[\begin{pmatrix} 0 \\ a_{21} \\ 0 \\ \vdots \\ 0 \end{pmatrix}, a_2, \dots, a_n \right] = (-1) a_{21} \det A(2,1)$$

$A(2,1)$ is A with its 2nd row and 1 col removed.

$$\text{, and } \det \left[\begin{pmatrix} 0 \\ \vdots \\ 0 \\ a_{n1} \end{pmatrix}, a_2, \dots, a_n \right] = (-1)^{n-1} a_{n1} \det A(n,1)$$

Definition $C_{ij} = (-1)^{i+j} \det A(i,j)$ \leftarrow 代数公式 公式
 where $A(i,j)$ is A with its i -th row, and j -th col removed.

$$\det A = a_{11}C_{11} + \cancel{a_{12}C_{12}} + \dots + \cancel{a_{1n}C_{1n}}, \quad \text{expansion}$$

more generally, $\det A = a_{1k}C_{1k} + \dots + a_{nk}C_{nk}$

let $C = (C_{ij}) \in \mathbb{R}^{n \times n}$, then.

$$(\det A) \frac{I}{\det A} = AC^T \Rightarrow A^{-1} = \frac{1}{\det A} C^T$$

Proof. $a_{1j}C_{1k} + \dots + a_{nj}C_{nk} = 0 \quad j \neq k.$

because $a_{1j}C_{1k} + \dots + a_{nj}C_{nk} = \det [a_1, \dots, a_j, \dots, a_n]$
 \uparrow
 k -th col.

\Rightarrow Big formula for $\det A$ for each permutation matrix P .

It has n "1"s, one in each col/row, from the product.

$$\pm a_{1s_1} a_{2s_2} \dots a_{ns_n} \Rightarrow \det A = \sum \pm a_{1s_1} \dots a_{ns_n} \quad \text{parity}$$

where $\begin{pmatrix} 1 & 2 & \dots & n \\ s_1 & s_2 & \dots & s_n \end{pmatrix}$ a permutation. \pm is determined by the

Cramer's rule.

Let $A(u, i)$ be matrix A with ^{its} i -th col replaced by the vector u , then

$$\det A(u, i) = u_1 C_{1i} + \dots + u_n C_{ni}, \text{ expansion}$$

C_{ij} the (i, j) -cofactor of A , and $u = \begin{pmatrix} u_1 \\ \vdots \\ u_n \end{pmatrix}$

Now from $Ax = b$, and $x = A^{-1}b$

$$= \frac{1}{\det A} C^T b = \begin{pmatrix} b_1 C_{11} + \dots + b_n C_{n1} \\ \vdots \\ b_1 C_{1n} + \dots + b_n C_{nn} \end{pmatrix} \frac{1}{\det A}$$

$$= \frac{1}{\det A} \begin{pmatrix} \det A(b, 1) \\ \vdots \\ \det A(b, n) \end{pmatrix}$$

Therefore, if A nonsingular, $Ax = b$ has sol $x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$

$$x_j = \frac{\det A(b, j)}{\det A}, \quad j=1, \dots, n.$$

Prob 1. $\det(I + uv^T) = 1 + u^T v$

Proof. Use householder, $Hu = \|u\|e_1$.

$$\begin{aligned} \det(I + uv^T) &= \det(H(I + uv^T)H) \\ &= \det\left(I + \|u\|e_1(Hv)^T\right) \text{ the matrix is upper tri.} \\ &= 1 + \|u\|e_1^T H v, \quad \text{but } He_1 = u/\|u\| \\ &= 1 + u^T v \end{aligned}$$

In particular, $\det(I - 2uv^T) = -1$, with $\|u\|=1$

Prob 2. Assume $a_i \neq 0, i=1, \dots, n$.

$$\begin{aligned} \det\begin{pmatrix} 1+a_1 & 1 & \dots & 1 \\ 1 & 1+a_2 & \dots & 1 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & \dots & 1+a_n \end{pmatrix} &= \det\left(\begin{pmatrix} a_1 & & & \\ & a_2 & & \\ & & \ddots & \\ & & & a_n \end{pmatrix} + \mathbb{1}\mathbb{1}^T\right) \\ &= (a_1 \dots a_n) \det\left(I + \begin{pmatrix} a_1^{-1} & & & \\ & \ddots & & \\ & & a_n^{-1} & \end{pmatrix} \mathbb{1}\mathbb{1}^T\right) \\ &= (a_1 \dots a_n) \left(1 + \sum_{i=1}^n \frac{1}{a_i}\right), \quad \text{what will be the result if} \\ &\quad \text{some } a_i = 0? \end{aligned}$$

Prob 3. If A is nonsingular,

$$\det \begin{pmatrix} A & B \\ C & D \end{pmatrix} = \det A \det (D - CA^{-1}B)$$

Proof. block elimination $\begin{pmatrix} A & B \\ C & D \end{pmatrix} \rightarrow \begin{pmatrix} A & B \\ 0 & D - CA^{-1}B \end{pmatrix}$

Prob 4. $\det (I_n - AB) = \det (I_m - BA)$

where $A \in \mathbb{R}^{n \times m}$, $B \in \mathbb{R}^{m \times n}$

Prob 5. Hadamard's inequality

$$\det A \leq \|a_1\| \|a_2\| \dots \|a_n\|.$$

Prob 6. let C be the cofactor matrix, then

$$\det C = (\det A)^{n-1}.$$

Proof $AC^T = (\det A)I.$

Extra material!

Determinants via QR decomposition. (outline)

If A is singular, define $\det A = 0$, and we only consider nonsingular matrices.

1. QR decomposition. There are unique Q ortho. and R upper tri with positive diagonal elements. s.t.

$$A = QR.$$

2. For an ortho Q , Q can be written as the product of a sequence of rotations and a permutation matrix. Define $\det Q$ as ± 1 or -1 according to the parity of the permutation matrix.

3. Define $\det A = (r_{11} \cdots r_{nn}) \cdot (\text{parity of } Q)$

We now outline a proof $\det AB = \det A \det B$

1) If $A = QL$, where L has positive diagonals

$$\text{then } \det A = (l_{11} \dots l_{nn}) (\text{parity}(Q))$$

$$2) \det \begin{pmatrix} A & B \\ 0 & C \end{pmatrix} = \det A \det B$$

Proof. $A = Q_A R_A$, ~~$B = Q_B R_B$~~ $C = Q_C R_C$

$$\begin{pmatrix} A & B \\ 0 & C \end{pmatrix} = \begin{pmatrix} Q_A & \\ & Q_B \end{pmatrix} \begin{pmatrix} R_A & Q_A^T B \\ 0 & R_C \end{pmatrix}$$

$$\text{parity} \left(\begin{pmatrix} Q_A & \\ & Q_B \end{pmatrix} \right) = \text{parity}(Q_A) \text{parity}(Q_B)$$

3) pre-multiply with $\begin{pmatrix} -1 & \\ & 1 \end{pmatrix}$ or $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ change the sign of the determinant. As a consequence

$$\det(-A) = (-1)^n \det A.$$

$$\det \left[\begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix} \begin{pmatrix} A & B \\ C & D \end{pmatrix} \right] = (-1)^n \det \begin{pmatrix} A & B \\ C & D \end{pmatrix}$$

$$4) \det \begin{pmatrix} A & B \\ C & D \end{pmatrix} \begin{pmatrix} I & X \\ 0 & I \end{pmatrix} = \det \begin{pmatrix} A & B \\ C & D \end{pmatrix} \quad \text{Proof. Use QR.}$$

$$\text{Now } \begin{pmatrix} I & B \\ A & 0 \end{pmatrix} \begin{pmatrix} I & -B \\ 0 & I \end{pmatrix} = \begin{pmatrix} I & 0 \\ A & -AB \end{pmatrix}$$

$$\text{This implies } (-1)^n \det A \det B = (-1)^n \det AB$$