

lecture 26. Properties of SVD.

SVD. Given $A \in \mathbb{R}^{m \times n}$, there are orthogonal matrices $U \in \mathbb{R}^{m \times m}$, $V \in \mathbb{R}^{n \times n}$ s.t.

$$AV = U\Sigma, \quad \Sigma = \begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_r & | & 0 \\ \hline & 0 & | & 0 & \end{pmatrix} \in \mathbb{R}^{m \times n}$$

$$\sigma_1 \geq \dots \geq \sigma_r > 0.$$

1. Let $m \geq n$. $\Sigma = \begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_r & | & 0 \\ \hline & 0 & | & 0 & \end{pmatrix}$

$\sigma_1, \dots, \sigma_r, \underbrace{0 \dots 0}_{n-r}$

are the singular values of A .

Let $m \leq n$, $\Sigma = \begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_r & | & 0 \\ \hline & 0 & | & 0 & \end{pmatrix}$

$\sigma_1, \dots, \sigma_r, \underbrace{0 \dots 0}_{m-r}$

are the singular values
of A .

In general, $\sigma_1, \dots, \sigma_r, \sigma_{r+1}, \dots, \sigma_{\min\{m, n\}}$

are the singular values of A .

2. let the $V = [v_1, \dots, v_n]$, $U = [u_1, \dots, u_m]$

Compare the i -th columns of both sides of.

$$(*) \quad AV = U\Sigma$$

We obtain $Av_i = \sigma_i u_i$

Taking transpose of both sides of (*), we

Obtain

$$(**) \quad A^T U = V\Sigma^T.$$

Compare the i -th columns of both sides of (**)

We obtain $A^T u_i = \sigma_i v_i$

(σ_i, u_i, v_i) is called the i -th, $i=1, \dots, \min\{n, m\}$
value
singular triplet of A .

3. SVD and Spectral decomposition.

from $AV = U\Sigma$, $A = U\Sigma V^T$.

we obtain $ATA = (U\Sigma V^T)^T (U\Sigma V^T)$

$$= V\Sigma^T U^T U\Sigma V^T$$

$$= V\Sigma^T \Sigma V^T = V \begin{pmatrix} \sigma_1^2 & & \\ & \ddots & \\ & & \sigma_r^2 \\ 0 & \cdots & 0 \end{pmatrix} V^T$$

the spectral decomposition of ATA .

i.e., V are the eigenvectors of ATA ,

ATA eigenvalues are

$$\sigma_1^2, \dots, \sigma_r^2, \underbrace{0, \dots, 0}_{n-r}$$

$$\text{Similarly, } AAT = U \begin{pmatrix} \sigma_1^2 & & \\ & \ddots & \\ & & \sigma_r^2 & \\ & & & 0 & \end{pmatrix} U^\top$$

U are the eigenvectors of AAT , and its eigenvalues are

$$\sigma_1^2, \dots, \sigma_r^2, \underbrace{0, \dots, 0}_{m-r}$$

4. Four fundamental subspaces of $A \in \mathbb{R}^{m \times n}$

$$r=r(A), \quad U=[u_1, \dots, u_m], \quad V=[v_1, \dots, v_n]$$

$$C(A) = \text{Span}\{u_1, \dots, u_r\}$$

$$N(A) = \text{Span}\{v_{r+1}, \dots, v_n\}$$

$$C(A^\top) = \text{Span}\{v_1, \dots, v_r\}$$

$$N(A^\top) = \text{Span}\{u_{r+1}, \dots, u_m\}$$

5. linear system $Ax=b$ and SVD.

plug in $A = U\Sigma V^T$ into $Ax=b$.

$$U\Sigma V^T x = b \Rightarrow \Sigma V^T x = U^T b, (*)$$

let $V^T x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n$, $U^T b = \begin{pmatrix} b_1 \\ \vdots \\ b_m \end{pmatrix} \in \mathbb{R}^m$

(*) implies $\left(\begin{array}{c|c} \sigma_1 & x_1 \\ \vdots & \vdots \\ \sigma_r & x_r \\ \hline 0 & 0 \\ \vdots & \vdots \\ 0 & 0 \end{array} \right) \begin{pmatrix} x_1 \\ \vdots \\ x_r \\ \hline x_{r+1} \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ \vdots \\ b_r \\ \hline b_{r+1} \\ \vdots \\ b_m \end{pmatrix}$

$Ax=b$ has a solution iff $b_{r+1} = \dots = b_m = 0$.

Otherwise, let's look at least squares problem

$$\|b - Ax\|^2 = \|U^T(b - Ax)\|^2$$

$$= \left\| \begin{pmatrix} b_1 \\ \vdots \\ b_r \\ \hline b_{r+1} \\ \vdots \\ b_m \end{pmatrix} - \left(\begin{array}{c|c} \sigma_1 & x_1 \\ \vdots & \vdots \\ \sigma_r & x_r \\ \hline 0 & 0 \\ \vdots & \vdots \\ 0 & 0 \end{array} \right) \begin{pmatrix} x_1 \\ \vdots \\ x_r \\ \hline x_{r+1} \\ \vdots \\ x_n \end{pmatrix} \right\|^2$$

$$= \| \begin{pmatrix} b_1 \\ \vdots \\ b_r \\ \vdots \\ b_m \end{pmatrix} - \begin{pmatrix} \sigma_1 & & & \\ & \ddots & & \\ & & \sigma_r & \\ & & & \ddots \\ & & & & \sigma_n \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_r \\ \vdots \\ x_n \end{pmatrix} \|^2 + \| \begin{pmatrix} b_{r+1} \\ \vdots \\ b_m \end{pmatrix} \|^2$$

the above is minimized if. $x_i = \frac{b_i}{\sigma_i}$, $i=1, \dots, r$.

A general solution for the least squares problem.

$$x = V \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = V \begin{pmatrix} \frac{b_1}{\sigma_1} \\ \vdots \\ \frac{b_r}{\sigma_r} \\ \hline x_{r+1} \\ \vdots \\ x_n \end{pmatrix}$$

$$= \left(\frac{b_1}{\sigma_1} \right) v_1 + \dots + \left(\frac{b_r}{\sigma_r} \right) v_r + x_{r+1} v_{r+1} + \dots + x_n v_n$$

where x_{r+1}, \dots, x_n arbitrary.

Or using subspace notation

$$x \in \underbrace{\left(\frac{b_1}{\sigma_1} \right) v_1 + \dots + \left(\frac{b_r}{\sigma_r} \right) v_r}_{\text{a special solution}} + \underbrace{\text{Span}\{v_{r+1}, \dots, v_n\}}_{N(A)}$$

6. for symmetric $A = A^T \in \mathbb{R}^{n \times n}$

for $x \neq 0$, $R(x) = \frac{x^T A x}{x^T x}$ is called a Rayleigh quotient.

In your homework II, you showed.

$$\lambda_{\min} \leq R(x) \leq \lambda_{\max}$$

where λ_{\min} and λ_{\max} are the smallest and largest eigenvalues of A , respectively.

Now consider $A^T A$. $x^T A^T A x = \|A x\|^2$

and $\frac{x^T A^T A x}{x^T x} = \left(\frac{\|A x\|}{\|x\|} \right)^2$

eigenvalues of $A^T A$ are $\sigma_1^2, \dots, \sigma_r^2, 0, \dots, 0$,

Hence $\sigma_{\min} \leq \frac{\|A x\|}{\|x\|} \leq \sigma_{\max}$

where σ_{\max} , and σ_{\min} are the smallest and largest singular values of A , respectively.

$\sigma_{\max}(A) = \max_{x \neq 0} \frac{\|Ax\|}{\|x\|}$ is defined to be

the spectral norm (or 2-norm) of A . $\sigma_{\max}(A) = \|A\|_2$

There's another norm of $A \in \mathbb{R}^{m \times n}$

$$\|A\|_F^2 = \sum_{i,j} a_{ij}^2 \quad (\text{Sum of squares of all elements of } A)$$

i) $\|A\|_F^2 = \text{trace}(A^T A) = \text{trace}(A A^T)$

$$= \sum_{i=1}^{\min(m,n)} \sigma_i^2 \geq \|A\|_2^2 = \sigma_{\max}^2(A)$$

$$7. A = \sigma_1 u_1 v_1^T + \cdots + \cancel{\sigma_{m+1} u_{m+1} v_{m+1}^T} + \cdots + \sigma_r u_r v_r^T$$

decomposition as a sum of r rank-1 matrices

Proof. $A = U\Sigma V^T$

$$= [\sigma_1 u_1, \dots, \sigma_r u_r, 0 \dots 0] V^T$$

$$= \sigma_1 u_1 v_1^T + \cdots + \sigma_r u_r v_r^T$$

8. for $k \leq r = \text{rank}(A)$. let.

$$A_k = \sigma_1 u_1 v_1^T + \cdots + \sigma_k u_k v_k^T$$

Then 1) $\text{rank}(A_k) = k$.

$$\|A - A_k\| = \min_{\text{rank}(B) \leq k} \|A - B\|$$

The norm $\|\cdot\|$ can be $\|\cdot\|_2$, $\|\cdot\|_F$.

or ~~spectr~~ Nuclear Norm $\|A\|_N = \sigma_1 + \cdots + \sigma_r$