

lecture 6



solving linear systems

Big picture

Triangular systems are easy to solve by back-substitution or forward-substitution

Gaussian elimination factorize A as

$$A = LU \quad \left(\begin{array}{l} \text{or more generally,} \\ PA = LU \end{array} \right)$$

where L is lower triangular, and U is upper triangular. Then

$$Ax = b \Leftrightarrow LUx = b.$$

$$\text{let } c = Ux \Rightarrow \begin{cases} Lc = b \\ Ux = c \end{cases}$$

Geometry of Solving linear systems

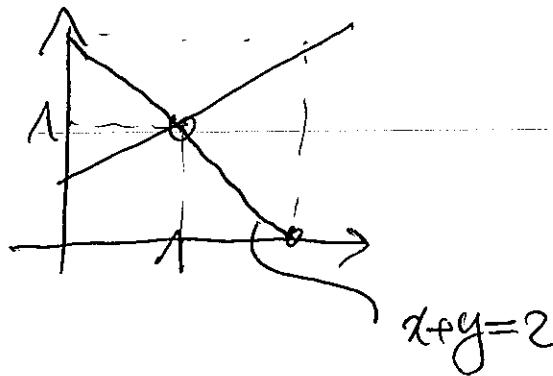
2x2 cases

three possibilities

i) one solution

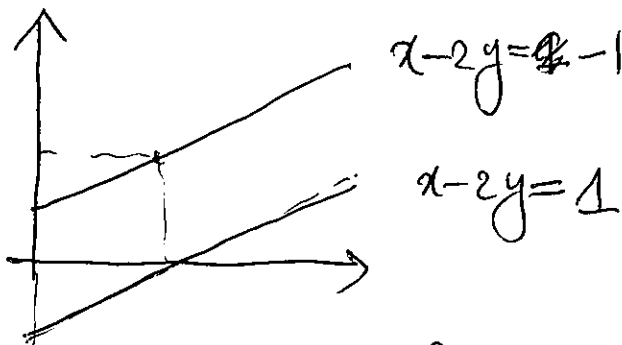
$$x - 2y = 1$$

$$x + y = 2$$



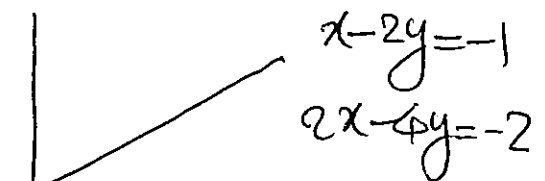
$$A = \begin{bmatrix} 1 & -2 \\ 1 & 1 \end{bmatrix}, b = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

ii) no solution



$$A = \begin{bmatrix} 1 & -2 \\ 1 & -2 \end{bmatrix}, b = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

iii) solution is a line



$$A = \begin{bmatrix} 1 & -2 \\ 1 & -2 \end{bmatrix}, b = \begin{bmatrix} -1 \\ -2 \end{bmatrix}$$

Back substitution for solving $Ux=c$

(4)

$$U = \begin{pmatrix} u_{11} & \dots & u_{1n} \\ & u_{22} & \dots & u_{2n} \\ & & \dots & \\ & & & u_{nn} \end{pmatrix}$$

$$u_{11}x_1 + \dots + u_{1n}x_n = c_1$$

$$u_{22}x_2 + \dots + u_{2n}x_n = c_2$$

\vdots

$$u_{nn}x_n = c_n$$

from the last equation: if $u_{nn} \neq 0$, $x_n = c_n / u_{nn}$

next to the last eq:

$$u_{n-1,n-1}x_{n-1} + u_{n-1,n}x_n = c_{n-1}$$

$$x_{n-1} = (c_{n-1} - u_{n-1,n}x_n) / u_{n-1,n-1}$$

\vdots

$$x_1 = (c_1 - u_{12}x_2 - \dots - u_{1n}x_n) / u_{11}$$

Example

$$\begin{pmatrix} 2 & 3 & 4 \\ 0 & 5 & 6 \\ 0 & 0 & 7 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 19 \\ 17 \\ 14 \end{pmatrix}$$

Write $Ax = b$ row-wise (5)

$$A = \begin{pmatrix} A_1 \\ \vdots \\ A_n \end{pmatrix} \quad A_i \in \mathbb{R}^{1 \times n}$$

$$Ax = b \Leftrightarrow \begin{cases} A_1 \cdot x = b_1 \\ \vdots \\ A_n \cdot x = b_n \end{cases}$$

Subtract α x equation (1) from equation (2).

$$A_2 \cdot x - \alpha \cdot (A_1 \cdot x) = b_2 - \alpha b_1.$$

$$\text{New eq (2)} = (A_2 - \alpha A_1) \cdot x = b_2 - \alpha b_1.$$

$$\tilde{A} = \begin{pmatrix} A_1 \\ A_2 - \alpha A_1 \\ \vdots \\ A_n \end{pmatrix} \quad \tilde{A}x = \tilde{b}$$

$$\tilde{b} = \begin{pmatrix} b_1 \\ b_2 - \alpha b_1 \\ \vdots \\ b_n \end{pmatrix}$$

and

$$Ax = b$$

have the same solutions

Matrix format

$$E_{21} A = \begin{pmatrix} 1 & & & \\ -\alpha & 1 & & \\ & & \ddots & \\ & & & 1 \end{pmatrix} \begin{pmatrix} A_1 \\ A_2 \\ \vdots \\ A_n \end{pmatrix} = \begin{pmatrix} A_1 \\ A_2 - \alpha A_1 \\ \vdots \\ A_n \end{pmatrix}$$

$$E_{21} b = \begin{pmatrix} 1 & & & \\ -\alpha & 1 & & \\ & & \ddots & \\ & & & 1 \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 - \alpha b_1 \\ \vdots \\ b_n \end{pmatrix}$$

order of elimination

Choose α s.t. the first element of $A_2 - \alpha A_1$ is zero. (6)

$A_2 - \alpha A_1$ is zero.

$$a_{21} - \alpha a_{11} = 0 \Rightarrow \alpha = \frac{a_{21}}{a_{11}}$$

Example. $A = \begin{bmatrix} 2 & 3 & 4 \\ 4 & 11 & 14 \\ 2 & 8 & 17 \end{bmatrix}$, $b = \begin{bmatrix} 19 \\ 55 \\ 50 \end{bmatrix}$

$$E_{21} = \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad E_{21}A = \begin{pmatrix} 2 & 3 & 4 \\ 0 & 5 & 6 \\ 2 & 8 & 17 \end{pmatrix}$$

$$E_{21}b = \begin{pmatrix} 19 \\ 17 \\ 50 \end{pmatrix}$$

$$E_{31} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix} \quad E_{31}(E_{21}A) = \begin{pmatrix} 2 & 3 & 4 \\ 0 & 5 & 6 \\ 0 & 5 & 13 \end{pmatrix}$$

$$E_{31}(E_{21}b) = \begin{pmatrix} 19 \\ 17 \\ 31 \end{pmatrix}$$

$$E_{32} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix} \quad U = \begin{pmatrix} 2 & 3 & 4 \\ 0 & 5 & 6 \\ 0 & 0 & 7 \end{pmatrix} \quad c = \begin{pmatrix} 19 \\ 17 \\ 14 \end{pmatrix}$$

zero-pivot.

⑦

$$\begin{bmatrix} 2 & 3 & 4 \\ 4 & 6 & 14 \\ 2 & 8 & 17 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 3 & 4 \\ 0 & 0 & 6 \\ 0 & 5 & 13 \end{bmatrix} \equiv B.$$

$$P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$PB = \begin{pmatrix} 2 & 3 & 4 \\ 0 & 5 & 13 \\ 0 & 0 & 8 \end{pmatrix}$$

However, $A^* = \begin{pmatrix} 2 & 3 & 4 \\ 4 & 6 & 14 \\ 2 & 3 & 17 \end{pmatrix} \xrightarrow{U} \begin{pmatrix} 2 & 3 & 4 \\ 0 & \underline{0} & 6 \\ 0 & 0 & 13 \end{pmatrix} = U^*$

$\text{rank}(A^*) < 3$. not of full-rank. (or nonsingular)

Th. A triangular matrix U is nonsingular iff. all its diagonal elements are nonzero.

Example. For which three numbers a will elimination fail to give three pivot

$$A = \begin{pmatrix} a & 2 & 3 \\ a & a & 4 \\ a & a & a \end{pmatrix} \rightarrow \begin{pmatrix} a & 2 & 3 \\ 0 & a-2 & 1 \\ 0 & a-2 & a-3 \end{pmatrix}$$

$$\begin{pmatrix} a & 2 & 3 \\ 0 & a-2 & 1 \\ 0 & 0 & a-4 \end{pmatrix}$$

a=0, or a=2, or a=4.

Example which g makes this system singular and which t gives it infinitely many sol?

Find the sol that has z=1.

$$\begin{aligned} x + 4y - 2z &= 1 \\ x + 7y - 6z &= 6 \\ 3y + gz &= t \end{aligned} \quad \begin{pmatrix} 1 & 4 & -2 \\ 1 & 7 & -6 \\ 0 & 3 & g \end{pmatrix} \quad \begin{pmatrix} 1 \\ 6 \\ t \end{pmatrix}$$

$$\begin{pmatrix} 1 & 4 & -2 \\ 0 & 3 & -4 \\ 0 & 3 & g \end{pmatrix} \quad \begin{pmatrix} 1 \\ 5 \\ t \end{pmatrix}$$

g = -4 ⇒ singular

t = 5 ⇒ infinitely many sol

$$\begin{pmatrix} 1 & 4 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} -2 \\ -4 \end{pmatrix} \cdot \underset{z=1}{1} = \begin{pmatrix} 1 \\ 5 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 4 & -2 \\ 0 & 3 & -4 \\ 0 & 0 & g+4 \end{pmatrix} \quad \begin{pmatrix} 1 \\ 5 \\ t-5 \end{pmatrix}$$