

Lecture 23

Eigenvalue II: Spectral Decomposition

谱分解

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Today's Lecture: Outline

Main topic: Spectral Theorem

1. Eigenbasis

2. Spectral Theorem

Today's Lecture: Learning Goals

After the lecture, you should be able to

1. Provide an example where eigenvectors do not form a basis
2. Describe the spectral decomposition and related properties
3. Explain the main proof steps of spectral decomposition

Review

Eigenvalues and Eigenvectors

Definition 21.1 (Eigenvalues and Eigenvectors)

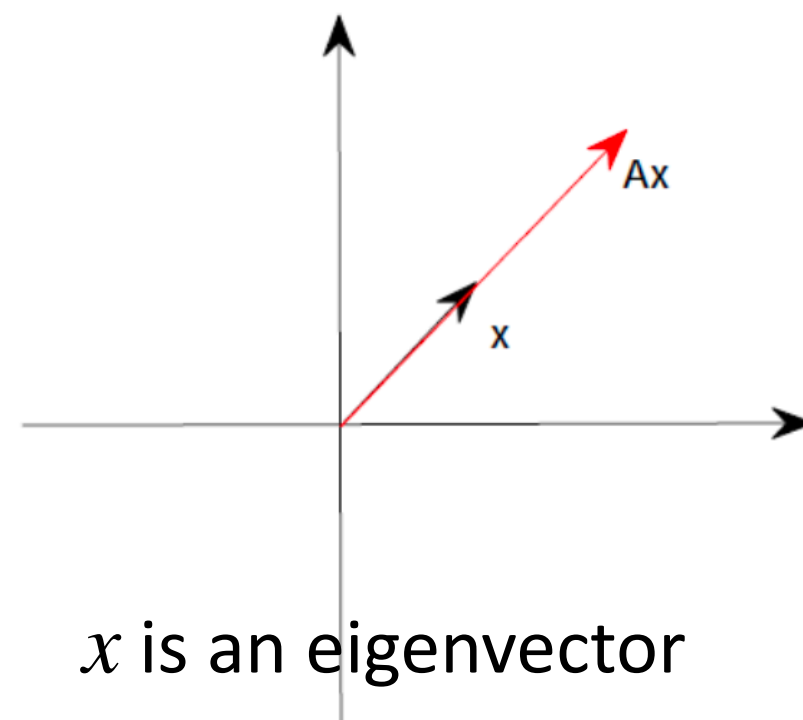
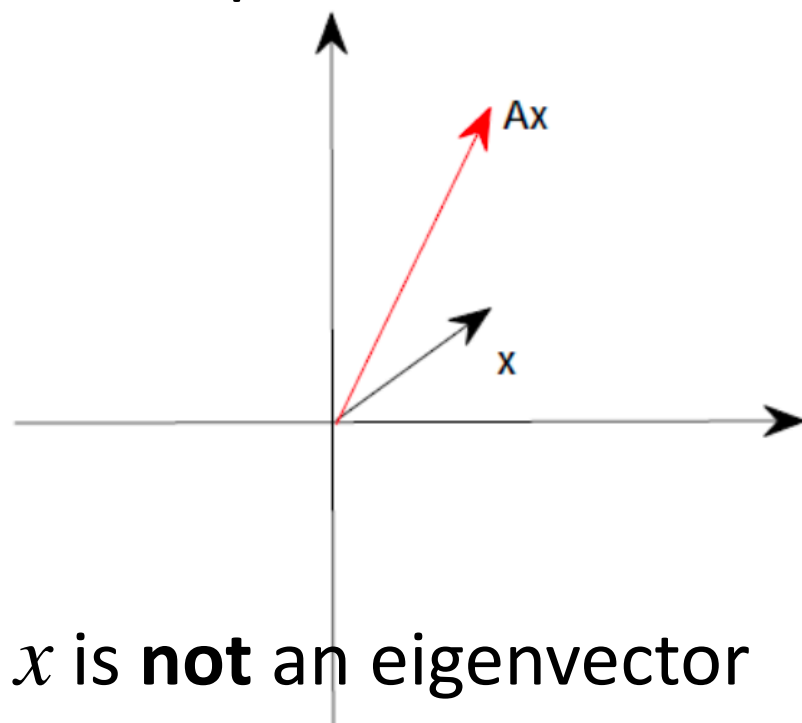
Let $A \in \mathbb{C}^{n \times n}$ be a square matrix.

If there exists a scalar λ ($\in \mathbb{R}$ or \mathbb{C}) and a **nonzero** vector x such that

$$Ax = \lambda x,$$

then λ is called a (real or complex) **eigenvalue** and x is called an **eigenvector** with respect to (or associated with; corresponding to) λ .

\mathbb{C} := set of complex numbers



General Procedure to Find Eigenvalues/Eigenvectors

Step 1: Solve $\det(A - \lambda I) = 0$ and get n roots $\lambda_1, \dots, \lambda_n$
Solving single-var polynomial. deg n

Step 2: For each λ_i , find the eigenspace $\text{Null}(\lambda_i I - A)$
Solving up to n linear systems. $A \chi_i = \lambda \chi_i$

Any nonzero vector in $\text{Null}(\lambda_i I - A)$ is an eigenvector
corresponding to λ_i

$$\text{Null}(\lambda_i I - A) = \left\{ \begin{array}{l} \text{eigenvectors of } A \text{ with} \\ \text{respect to the eigenvalue } \lambda_i \end{array} \right\} \cup \{0\}$$

Eigenvalues and Eigenvectors

$$\det(\lambda I - A)$$

Characteristic polynomial $p_A(\lambda) = \det(A - \lambda I)$ is a degree- n polynomial with coefficient of λ^n being $(-1)^n$.

Fact:

Any $n \times n$ (no matter real or complex) matrix A has exactly n **complex eigenvalues** (counting multiplicity).

Here, multiplicity of λ_j is the power k of the term $(\lambda - \lambda_j)$ in the decomposition of the characteristic polynomial $p_A(\lambda) = (-1)^n \prod_{j=1}^n (\lambda - \lambda_j)^{k_j}$.

$$ax^2 + bx + c = a(x - x_1)(x - x_2)$$

$$x_1 = x_2 = a(x - x_1)^2$$

Part 1 Eigenbasis

Multiset [多重集]

~~{a, a, b}~~

~~{1, 1, 2}~~

Multiset A **multiset** is a modification of the concept of a set that, unlike a set, allows for multiple instances for each of it.

Can use $\#\{a_1, a_2, \dots\}$ to denote a multiset; though some ppl just use $\{a_1, a_2, \dots\}$

$\#\{1, 1, 2\}$.

Multiplicity: If an element appears k times in the multiset, then the **multiplicity** of the element in the multiset is k .

Multiset [多重集]

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Examples:

In the multiset $\#\{a, a, b\}$, the element a has multiplicity 2 and b has multiplicity 1.

In the multiset $\#\{a, a, a, b, b, b\}$, a and b both have multiplicity 3.

The set $\{a, b\}$ contains only elements a and b .

Each having multiplicity 1 when $\{a, b\}$ is seen as a multiset $\#\{a, a, a, b, b, b\}$.

Order does not matter: $\#\{a, a, b\}$ and $\#\{a, b, a\}$ denote the same multiset.

$A = \begin{bmatrix} 1 & & \\ & 1 & \\ & & 2 \end{bmatrix}$ has eigenvalues 1, 1, 2

A has eigenvalues 1, 2.

$B = \begin{bmatrix} 1 & \\ & 2 \end{bmatrix}$ has eigenvalue 1, 2.

Can we say: A and B have the same eigenvalues?

No, if "have the same eigenvalues" means "have the same multiset of eigenvalues".

Linear Space over Complex Domain

Recall:

Definition of Linear space over \mathbb{R} .

scalar product

$$\alpha \cdot v, \alpha \in \mathbb{R}, v \in V.$$

A linear space over \mathbb{C} is defined in a similar way:

just change $\in \mathbb{R}$ to $\in \mathbb{C}$

scalar product

$$\alpha \cdot v, \alpha \in \mathbb{C}, v \in V.$$

For completeness, we state the full definition in the next slide.

$$\text{e.g. } i \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} i \\ 2i \end{pmatrix}$$

$$(1+i) \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} = \begin{bmatrix} (1+i) \cdot 2 & - \\ - & - \end{bmatrix}$$

Reading: Def: Linear Space over Complex Domain

Definition 23.3 (Linear space over \mathbb{C})

Suppose V is a set associated with two operations:

- (i) Addition "+": $\mathbf{u} + \mathbf{v} \in V, \forall \mathbf{u} \in V, \mathbf{v} \in V$.
- (ii) Scalar multiplication: $\alpha \mathbf{u} \in V, \forall \alpha \in \mathbb{C}, \mathbf{u} \in V$.

V is called a linear space over \mathbb{C} if the 8 axiom axioms hold:

(A1) $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}, \forall \mathbf{u}, \mathbf{v} \in V$.

(A2) $\mathbf{u} + (\mathbf{v} + \mathbf{w}) = (\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + \mathbf{v} + \mathbf{w}, \forall \mathbf{u}, \mathbf{v}, \mathbf{w} \in V$.

(A3) There exists a element $\mathbf{0}$ s.t. $\mathbf{u} + \mathbf{0} = \mathbf{u}, \forall \mathbf{u} \in V$.

(A4) If $\mathbf{u} \in V$, then there exists $-\mathbf{u} = (-1)\mathbf{u}$, s.t. $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$.

(A5) $\alpha(\mathbf{u} + \mathbf{v}) = \alpha\mathbf{u} + \alpha\mathbf{v}, \forall \alpha \in \mathbb{C}, \mathbf{u}, \mathbf{v} \in V$.

(A6) $(\alpha + \beta)\mathbf{u} = \alpha\mathbf{u} + \beta\mathbf{u}, \forall \alpha, \beta \in \mathbb{C}, \mathbf{u} \in V$.

(A7) $\alpha(\beta\mathbf{u}) = (\alpha\beta)\mathbf{u}, \forall \alpha, \beta \in \mathbb{C}, \mathbf{u} \in V$.

(A8) $1\mathbf{u} = \mathbf{u}$.

eg,
 \mathbb{C}^n is linear space
 $\begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix}, z_j \in \mathbb{C}$

Space \mathbb{C}

Complex number written as $z = a + bi$, where $i = \sqrt{-1}$

Complex conjugate of x [x 的共轭复数] is $\bar{z} = a - bi$

Modulus of z [z 的模] is $|z| = \sqrt{a^2 + b^2}$ [using a, b]
 $= z \cdot \bar{z}$ [using z, \bar{z}]

A complex number $x = a + bi$, where $i = \sqrt{-1}$

is a real number

iff $b = 0$, iff $x = \bar{x}$.

Space \mathbb{C}^n

A few statements about the complex vector space.

$\{e_1, e_2, e_3\}$ is still a basis of \mathbb{C}^3 .

$$\begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix} = z_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + z_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + z_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$\begin{bmatrix} 1 \\ i \end{bmatrix}$ and $\begin{bmatrix} i \\ -1 \end{bmatrix}$ are linearly dependent.

$$\begin{bmatrix} 1 \\ i \end{bmatrix} \cdot i = \begin{bmatrix} i \\ -1 \end{bmatrix} = \begin{bmatrix} i \\ -1 \end{bmatrix}$$

If $\mathbf{z} = (z_1, \dots, z_n) \in \mathbb{C}^n$, then $\bar{\mathbf{z}}^T \mathbf{z} = \sqrt{|z_1|^2 + \dots + |z_n|^2}$

$$\bar{\mathbf{z}}^T \mathbf{z} = [\bar{z}_1, \dots, \bar{z}_n] \begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix} = \bar{z}_1 z_1 + \dots + \bar{z}_n z_n = |z_1|^2 + \dots + |z_n|^2$$

Corollary: $\mathbf{z} = \mathbf{0}$ iff $\bar{\mathbf{z}}^T \mathbf{z} = 0$.

Judgment, $z \in \mathbb{C}^n$.

$$z = 0 \Leftrightarrow z^T z = 0,$$

False.

Big Picture About Eigenvalues & Eigenvectors

① exactly n complex eigenvalues.

(luckily).

~~②~~ How many eigenvectors? ∞ -many; not interesting.

③ How many independent eigenvectors?

at most n ; but is it always n ?

How Many Linearly Independent Eigenvectors?

Judgement:

Statement 1: An $n \times n$ matrix always has n linearly independent eigenvectors.

\mathbb{R}^n

n vec

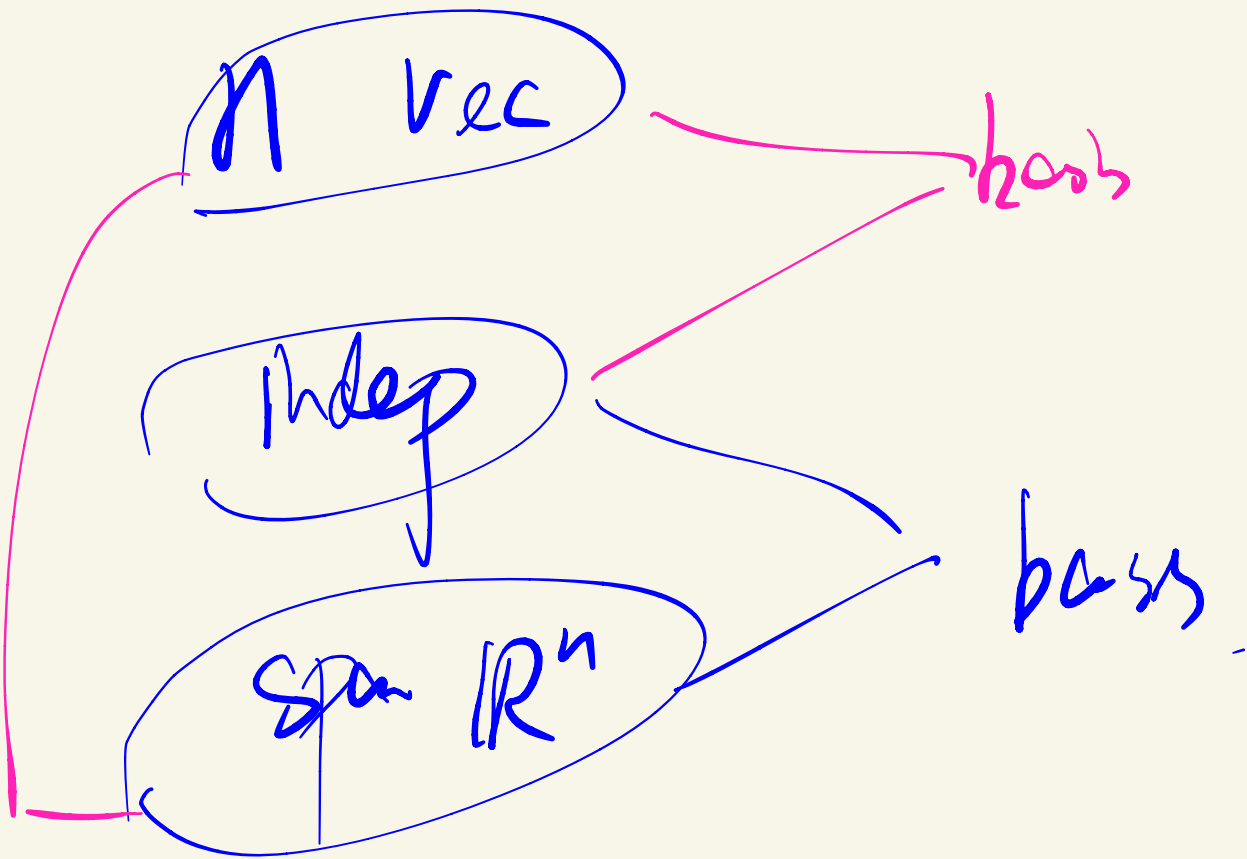
indep

span \mathbb{R}^n

basis

basis

basis



Example 1: Do Eigenvectors Form a Basis?

Example

$$A = \begin{bmatrix} 3 & 2 \\ 3 & -2 \end{bmatrix}$$

Two eigenvalues $\lambda_1 = 4$ and $\lambda_2 = 3$

(1). For $\lambda_1 = 4$,

For any $t \neq 0$, $x = t \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ is an eigenvector with respect to $\lambda_1 = 4$

(2). For $\lambda_2 = 3$,

For any $t \neq 0$, $x = t \begin{bmatrix} 1 \\ -3 \end{bmatrix}$ is an eigenvector with respect to $\lambda_2 = 3$

Do $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ -3 \end{bmatrix}$ form a basis of \mathbb{R}^2 ?

95%

yes

Are $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$ & $\begin{bmatrix} 1 \\ -3 \end{bmatrix}$ independent?

95% yes.

Example 2: Do Eigenvectors Form a Basis?

Example

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

Two eigenvalues $\lambda_1 = i$ and $\lambda_2 = -i$

(1). For $\lambda_1 = i$,

For any $t \neq 0$, $x = t \begin{bmatrix} 1 \\ i \end{bmatrix}$ is an eigenvector with respect to $\lambda_1 = i$

(2). For $\lambda_2 = -i$,

For any $t \neq 0$, $x = t \begin{bmatrix} 1 \\ -i \end{bmatrix}$ is an eigenvector with respect to $\lambda_2 = -i$

Do $\begin{bmatrix} 1 \\ i \end{bmatrix}$ and $\begin{bmatrix} 1 \\ -i \end{bmatrix}$ form a basis of \mathbb{C}^2 ? *Yes*

How Many Linearly Independent Eigenvectors?

Judgement:

Statement 1: An $n \times n$ matrix always has n linearly independent eigenvectors.

You may ask: real or complex?

Judgement:

Statement 2: An $n \times n$ real matrix always has n linearly independent **real** eigenvectors.

False (by example 2, no real eigenvectors for some matrix)

Judgement:

Statement 3: An $n \times n$ real matrix always has n linearly independent **complex** eigenvectors (note: including real eigenvectors).

False (by example 3, next page)

Example 3: Do Eigenvectors Form a Basis?

Example

$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

Eigenvalues are

$$\det(\lambda I - A) = \begin{vmatrix} \lambda - 1 & -1 \\ 0 & \lambda - 1 \end{vmatrix} = (\lambda - 1)^2 = 0 \Rightarrow \lambda = 1.$$

Eigenvectors are

$$\begin{pmatrix} \lambda - 1 & -1 \\ 0 & \lambda - 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \Leftrightarrow x_2 = 0$$

$$\text{Null}(\lambda I - A) = \left\{ \begin{pmatrix} t \\ 0 \end{pmatrix} \mid t \in \mathbb{C} \right\}.$$

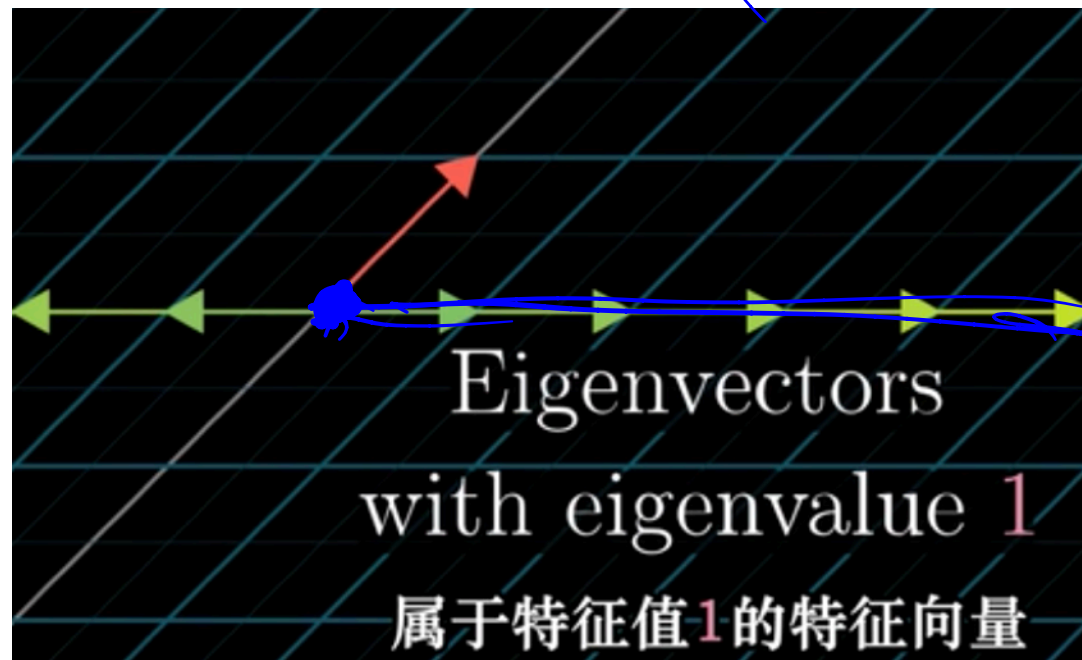
Can you find two eigenvectors that form a basis of \mathbb{R}^2 ? (\mathbb{C}^2)

No cannot span \mathbb{R}^2 (or \mathbb{C}^2)

Remark (advanced reading) This example is related to "Jordan form"
Interested students may search it; we do NOT teach it.

Eigenbasis may NOT exist

Fact: The (complex) eigenvectors of $\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$ do NOT form a basis.



(1, 0)

Eigenspace dimension $\dim(N(\lambda_1 I - A)) = 1$.

Multiplicity is 2.

Do Eigenvectors Form a Basis?

Eigenbasis:

A set of eigenvectors that can form a basis of whole space.

$(\mathbb{R}^n \text{ or } \mathbb{C}^n)$.

Fact:

基

For certain $n \times n$ matrices, the eigenbasis does NOT exist.

i.e. can find at most $(n-1)$ independent eigenvectors of A .

即
For some $n \times n$ matrices, eigenvectors can span \mathbb{C}^n
(can form a basis of \mathbb{C}^n).

Part II Spectral Decomposition

Sec. 6.4

for real symmetric matrices.

Lemma 23.1 If $Av_1 = \lambda_1 v_1, \dots, Av_n = \lambda_n v_n,$

where $A \in \mathbb{C}^{n \times n}, v_j \in \mathbb{C}^{n \times 1}, \lambda_j \in \mathbb{C}, j=1, \dots, n,$

then $AV = VD,$ where $V = [v_1, \dots, v_n] \in \mathbb{C}^{n \times n}, D = \text{diag}(\lambda_1, \dots, \lambda_n).$

Proof: $AV = A[v_1, \dots, v_n]$

$$= [Av_1, \dots, Av_n]$$

$$= [\lambda_1 v_1, \dots, \lambda_n v_n] \quad (**)$$

$$= [v_1, \dots, v_n] \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$$

$$= VD. \quad \square.$$

Lemma 23.2. If $AV = VD,$ where $V = [v_1, \dots, v_n] \in \mathbb{C}^{n \times n}, D = \text{diag}(\lambda_1, \dots, \lambda_n),$

then $Av_j = \lambda_j v_j, j=1, \dots, n.$

Proof: Reverse the chain of equalities in (**).

Orthonormal Eigenbasis

Claim 23.1 [orthonormal eigenbasis \Rightarrow symmetric matrix]

property of A

Eigenvectors of a real matrix A can form an orthonormal basis of \mathbb{R}^n .

$\Leftrightarrow A = VDV^T$ where D is a real diagonal matrix, V is a real orthogonal matrix.

Proof: " \Rightarrow " Suppose eigenvector v_1, \dots, v_n form an orthonormal basis of \mathbb{R}^n , then $V = [v_1, \dots, v_n]$ is an orthonormal matrix.

Suppose $Av_j = \lambda_j v_j$, where $\lambda_j \in \mathbb{C}$; then $\lambda_j \in \mathbb{R}$ (since $A, v_j \in \mathbb{R}$)

By Lemma 23.1, we have $AV = VD$, where $D = \text{diag}(\lambda_1, \dots, \lambda_n)$.

Then $A = VDV^{-1} = VDV^T$.

" \Leftarrow " Suppose $V = [v_1, \dots, v_n]$, $D = \text{diag}(\lambda_1, \dots, \lambda_n)$. Then $\{v_j\}$'s form an orthonormal basis.

By Lemma 23.2, we have $Av_j = \lambda_j v_j$, $j=1, \dots, n$. Thus $\{v_j\}$'s are eigenvectors!

\Rightarrow eigenvectors of A can form an orthonormal basis. \square

Corollary: If a real matrix A has an orthonormal eigenbasis, then A is a symmetric matrix.

What about the other direction?

Proof sketch of Claim 23.1.

$$\text{Fact } Av_j = \lambda_j v_j, \quad \forall j \in \{1, \dots, n\}$$
$$\Rightarrow AV = VD.$$

Next, $\{v_j\}$ orthonormal $\Rightarrow V = [v_1 \dots v_n]$
is orthogonal matrix.

$$AV = VD$$

$$\Rightarrow \underline{A} = VD \cdot \underline{V}^{-1} = \underline{VDV^T}$$

Proof of Corollary:

$$\underline{A^T} = (VDV^T)^T = (V^T)^T \underline{D^T} V^T$$
$$= VDV^T = A,$$

$$A = VV^T \quad \text{is symmetric}$$

since $A^T = (V^T)^T V^T = VV^T = A$.

$$A = VDV^T \text{ is also symmetric}$$

(if D is diagonal)

$$\begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$$

A: multiply j -th row
by λ_j

$$A \cdot \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$$

: multiply j -th column
by λ_j

Spectral Theorem

Theorem 23.1 [Spectral Theorem]

Any real symmetric matrix A can be written as

$$A = VDV^T \quad (*)$$

where D is a real diagonal matrix, V is a real orthogonal matrix.

$AV_j = \lambda_j v_j$ (*)
 $V = [v_1, \dots, v_n]$, v_j 's are eigenvectors
 $D = \text{diag}(\lambda_1, \dots, \lambda_n)$, λ_j 's are eigenvals

Vector form [practice]:

$$\begin{aligned}
 A = VDV^T &= [v_1, \dots, v_n] \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} \begin{bmatrix} v_1^T \\ \vdots \\ v_n^T \end{bmatrix} \quad \text{[column \& row form]} \\
 &= \underbrace{[\lambda_1 v_1, \dots, \lambda_n v_n]}_{1 \times n} \underbrace{\begin{bmatrix} v_1^T \\ \vdots \\ v_n^T \end{bmatrix}}_{n \times 1} \quad \text{[outer product]} \\
 &= \lambda_1 v_1 v_1^T + \dots + \lambda_n v_n v_n^T = \sum_{j=1}^n \lambda_j v_j v_j^T \quad (**).
 \end{aligned}$$

(*) and (**): Eigenvalue decomposition (EVD) or eigendecomposition of A .

Remark on Vector Form of EVD

Matrix product (Lec 5-6).

$$AB = \sum_{j=1}^n a_j b_j^T \quad (\text{sum of outer products})$$

Mid-term exam:

Express $BB^T = I$ by column form $B = [v_1, \dots, v_n]$

$$I = BB^T = \left[\overbrace{v_1, \dots, v_n}^{n \times n} \right] \left[\overbrace{v_1^T, \dots, v_n^T}^{n \times 1} \right] = \sum_{j=1}^n v_j v_j^T,$$

Here: $A = VDV^T = \sum_{j=1}^n \lambda_j v_j v_j^T$, (weighted sum of outer products),

Two ways to check v_j 's are eigenvectors.

Method 1, by Lemma 23.2

Method 2:

If $A = \sum_{j=1}^n \lambda_j v_j v_j^T$, and $\{v_j\}$ orthonormal set,
($v_j \perp v_k, \forall j \neq k$,
 $\|v_j\| = 1$),
then $A v_j = \lambda_j v_j$.

Proof

$$\begin{aligned} A v_1 &= (\lambda_1 v_1 v_1^T + \dots + \lambda_n v_n v_n^T) v_1 \\ &= \lambda_1 v_1 v_1^T v_1 + \lambda_2 v_2 v_2^T v_1 + \dots + \lambda_n v_n v_n^T v_1 \\ &= \lambda_1 v_1 + 0 + \dots + 0 \\ &= \lambda_1 v_1. \end{aligned}$$

Properties of Real Symmetric Matrices

Real Symmetric Matrices

Property 1: All eigenvalues are real.

Property 2: All eigenvectors are real.
(more rigorously, can be real)

Property 3: Eigenvectors can form an orthonormal basis of \mathbb{R}^n .
(or \mathbb{C}^n)

Together: A can be written as

$$A = VDV^T = \sum_{j=1}^n \lambda_j v_j v_j^T.$$

General Matrices

Eigenvalues can be complex.

Eigenvectors can be complex.

Eigenvectors may NOT form basis of \mathbb{C}^n .

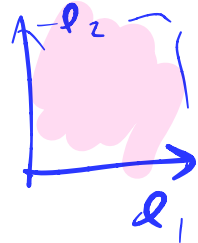
A can be written as

$$\sum_{j=1}^n \lambda_j v_j v_j^T$$

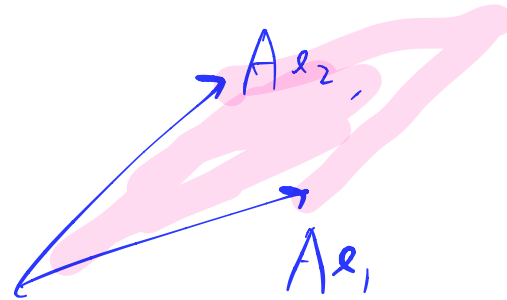
Geometry View

Previous lectures

Basis $\{e_1, e_2\}$

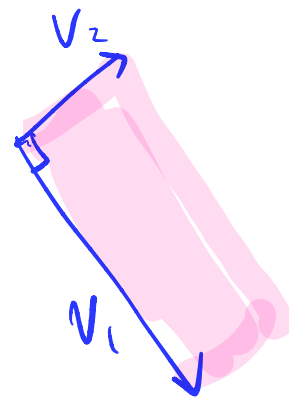
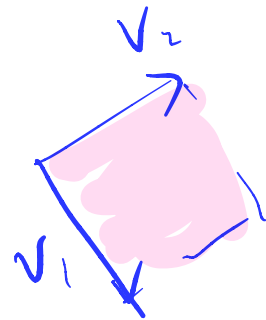


shape of tiles change



Here: For symmetric $A \in \mathbb{R}^{n \times n}$:

Basis $\{v_1, v_2\}$



$$x = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \underline{\underline{(x_1, x_2)}}$$

shape does not change (too much)
directions stay.

$$Ax = (v_1, v_2) (\lambda_1 x_1, \lambda_2 x_2).$$

Proof of Spectral Theorem

The full proof of spectral theorem is skipped here
(It requires a bit trick and induction)

$$\lambda_j \neq \lambda_k, \forall j \neq k.$$

Next, we **only** prove the case for **distinct eigenvalues.**

only prove the case for **distinct eigenvalues.**

only prove the case for **distinct eigenvalues.**

Proof of EVD for Distinct Eigenvalues (I): Real Eigenvalues

Assumption 23.1: $A \in \mathbb{R}^{n \times n}$ and $A = A^T$.

Property 23.1: Under Assump. 23.1, all eigenvalues are real.

Analysis:

What we know:

Suppose $A\mathbf{v} = \lambda\mathbf{v}$,

play with it by multiplying sth.

Want to prove: $\lambda \in \mathbb{R}$.

where $\lambda \in \mathbb{C}$, $\mathbf{v} \in \mathbb{C}^{n \times 1} \setminus \{\mathbf{0}\}$.

$$A = A^T \Rightarrow \underline{v^T A} = \underline{v^T A^T} = \underline{\lambda v^T} \quad (1)$$

$$A = \bar{A} \Rightarrow A \bar{v} = \bar{A} \bar{v} = \bar{\lambda} \bar{v} \quad (2)$$

Combine $v^T \bar{v}$ and $\bar{A} \bar{v}$

Proof of EVD for Distinct Eigenvalues (I): Real Eigenvalues

Assumption 23.1: $A \in \mathbb{R}^{n \times n}$ and $A = A^T$. Fact: $\bar{v}^T v = 0$ iff $v = 0$.

$$v \neq 0 \Rightarrow \bar{v}^T v \neq 0 \quad (3)$$

Proof of Property 23.1:

Suppose $A\mathbf{v} = \lambda\mathbf{v}$, where $\lambda \in \mathbb{C}$, $\mathbf{v} \in \mathbb{C}^{n \times 1}$. Want to prove: $\lambda \in \mathbb{R}$.

Use two ways to compute $\bar{\mathbf{v}}^T A\mathbf{v}$.

First way: $\bar{\mathbf{v}}^T A\mathbf{v} = \bar{\mathbf{v}}^T (A \cdot \mathbf{v}) = \bar{\mathbf{v}}^T \cdot \lambda \cdot \mathbf{v} = \lambda \bar{\mathbf{v}}^T \mathbf{v}$

Second way: $\bar{\mathbf{v}}^T A\mathbf{v} = (\bar{\mathbf{v}}^T A) \mathbf{v} = (\bar{\mathbf{v}}^T A^T) \mathbf{v}$

Symmetric
↓
 $= (A\bar{\mathbf{v}})^T \mathbf{v}$

real
←
 $= (\bar{A}\bar{\mathbf{v}})^T \mathbf{v}$

$= \bar{\lambda} \cdot \bar{\mathbf{v}}^T \mathbf{v}$

$\lambda \cdot \bar{\mathbf{v}}^T \mathbf{v}$

$\lambda = \bar{\lambda}$

i.e., $\lambda \in \mathbb{R}$.

Proof of EVD for Distinct Eigenvalues (I): Real Eigenvectors

Assumption 23.1 (1st part): $A \in \mathbb{R}^{n \times n}$.

Property 23.2: For any ^{real} eigenvalue of A , there exists a real eigenvector with respect to this eigenvalue.

Proof of Property 23.2:

Suppose $A\mathbf{v} = \lambda\mathbf{v}$, where $\lambda \in \mathbb{R}$, $\mathbf{v} \in \mathbb{C}^{n \times 1} \setminus \{\mathbf{0}\}$.

Suppose $\mathbf{v} = x + y \cdot i$,
where $x, y \in \mathbb{R}^{n \times 1}$; one of x, y is $\neq 0$. ①

$$A(x + yi) = \lambda(x + yi)$$

$$\Leftrightarrow \underbrace{Ax}_{\text{real}} + \underbrace{Ay \cdot i}_{\text{real}} = \underbrace{\lambda x}_{\text{Prop 23.1}} + \underbrace{\lambda y \cdot i}_{\text{real}}$$

① \neq ②

$$\Leftrightarrow Ax = \lambda x, Ay = \lambda y. \text{ ②}$$

\Rightarrow One of x, y should be eigenvectors

Proof of EVD for Distinct Eigenvalues (III): Orthogonality

Assumption 23.1: $A \in \mathbb{R}^{n \times n}$ and $A = A^T$.

Property 23.3: Under Assumption 23.1, real eigenvectors corresponding to different eigenvalues are orthogonal.

Proof of EVD for Distinct Eigenvalues (III): Orthogonality

Assumption 23.1: $A \in \mathbb{R}^{n \times n}$ and $A = A^T$.

Property 23.3 Under Assumption 23.1, eigenvectors corresponding to different eigenvalues are orthogonal. *want* $\Rightarrow x_1^T x_2 = 0$

Proof: Suppose $Ax_1 = \lambda_1 x_1$, $Ax_2 = \lambda_2 x_2$, $\lambda_1 \neq \lambda_2$. Check $x_1^T Ax_2$.

① $Ax_1 = \lambda_1 x_1$ ② $Ax_2 = \lambda_2 x_2$ *Wanna!*

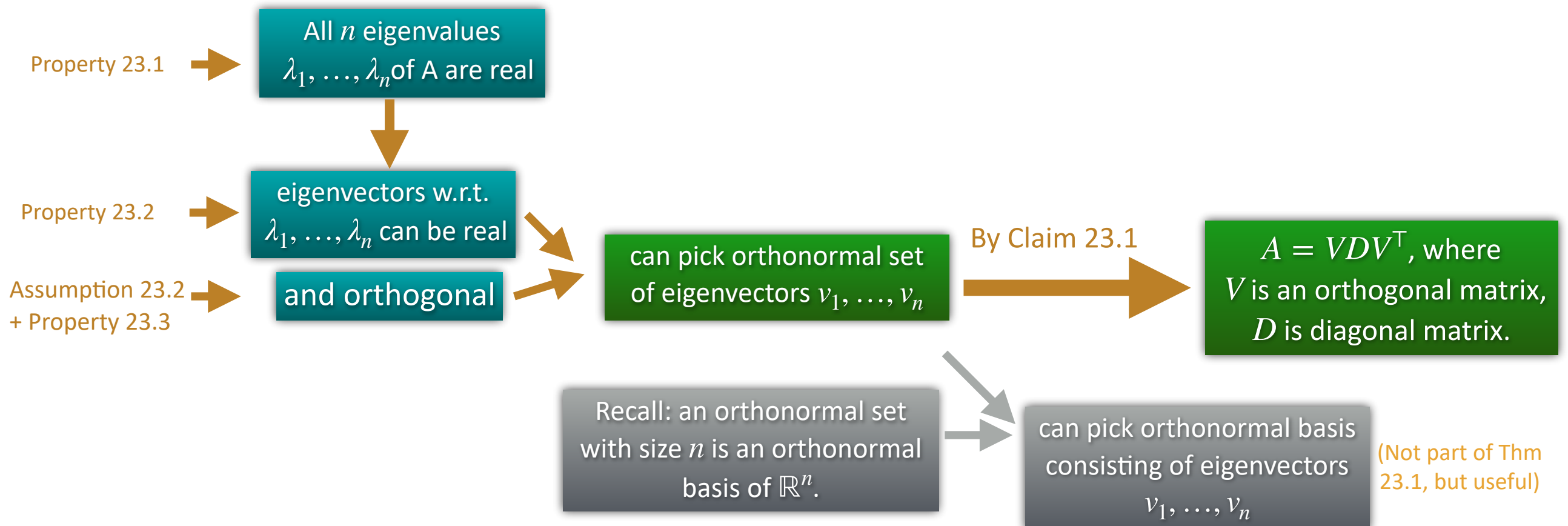
$$\begin{array}{ccc}
 \underbrace{x_1^T}_{(1 \times n)} \underbrace{A}_{n \times n} \underbrace{x_2}_{n \times 1} & & \\
 \parallel & \parallel & \\
 (x_1^T A) x_2 & & x_1^T (Ax_2) \\
 \parallel \xrightarrow{\text{symmetric}} & & \parallel \textcircled{2} \\
 (x_1^T A^T) x_2 & & \lambda_2 x_1^T x_2 \\
 \textcircled{1} & & \\
 \lambda_1 x_1^T x_2 & &
 \end{array}
 \Rightarrow x_1^T x_2 = 0,$$

EVD for Distinct Eigenvalues

Assumption 23.1: $A \in \mathbb{R}^{n \times n}$ and $A = A^T$.

Assumption 23.2: all eigenvalues of $A \in \mathbb{R}^{n \times n}$ are distinct.


Proof of Thm 23.1 under Assumption 23.2: (Combining Property 23.1, 23.2, 23.3)



So far, we **have** proved Thm 23.1 for **distinct eigenvalues**.

The proof for general case “any real symmetric matrix A can be written as

$A = VDV^T$ ” is SKIPPED.



Summary Today (Write Your Own)

One sentence summary:

Detailed summary:

Summary Today (Instructor)

One sentence summary:

We learned eigenbasis and spectral decomposition.

Detailed summary:

- i) For some matrices, there are n eigenvectors that form a basis, called eigenbasis.

Fact: Eigenbasis may or may NOT exist, for a given matrix.

- ii) Eigenvalue decomposition (特征值分解), or spectral decomposition.

A **real symmetric matrix** A can be written as

$$A = VDV^T = \sum_{j=1}^n \lambda_j v_j v_j^T$$

where